Plane Equation

• Given three points, they determine a plane

$$\mathbf{p}_{a} = \begin{bmatrix} x_{a} \\ y_{a} \\ z_{a} \end{bmatrix}$$
$$\mathbf{p}_{b} = \begin{bmatrix} x_{b} \\ y_{b} \\ z_{b} \end{bmatrix}$$
$$\mathbf{p}_{c} = \begin{bmatrix} x_{c} \\ y_{c} \\ z_{c} \end{bmatrix}$$

where p_a , p_b , and p_c are not co-linear!

Normal of the plane

$$\mathbf{n} = \frac{(\mathbf{p}_c - \mathbf{p}_a) \times (\mathbf{p}_b - \mathbf{p}_a)}{|(\mathbf{p}_c - \mathbf{p}_a) \times (\mathbf{p}_b - \mathbf{p}_a)|}$$
$$\mathbf{n} = \begin{bmatrix} A \\ B \\ C \end{bmatrix}$$

• Arbitrary point on the plane

$$\mathbf{p} = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

• Equation (implicit function)

$$f(x, y, z) = 0$$

• Plane equation derivation

$$(\mathbf{p} - \mathbf{p}_a) \star \mathbf{n} = 0$$
$$(x - x_a)A + (y - y_a)B + (z - z_a)C = 0$$
$$Ax + By + Cz - (Ax_a + By_a + Cz_a) = 0$$
$$Ax + By + Cz + D = 0$$

where

$$D = -(Ax_a + By_a + Cz_a)$$

• Explicit expression (if C is non-zero)

$$z = -\frac{1}{C}(Ax + By + D)$$

This can be generalized to both x and y

• Parametric representation

$$\mathbf{p}(u,v) = \mathbf{p}_a + (\mathbf{p}_b - \mathbf{p}_a)u + (\mathbf{p}_c - \mathbf{p}_a)v$$

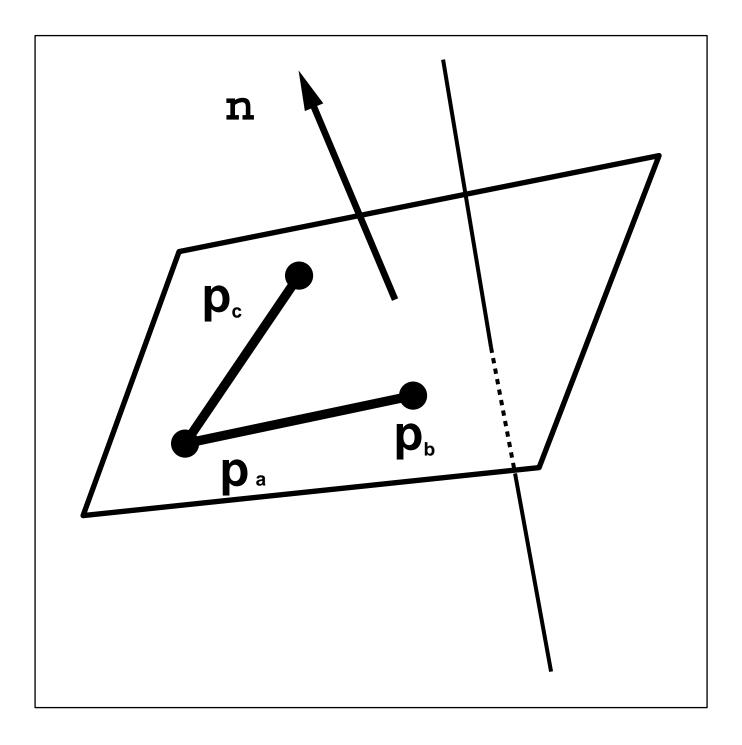
• Line-Plane intersection

$$l(u) = p_0 + (p_1 - p_0)u$$

(n) * (p_0 + (p_1 - p_0)u) + d = 0
$$u = -\frac{n * p_0}{n * p_1 - n * p_0} = -\frac{plane(p_0)}{plane(p_1) - plane(p_0)}$$

• Parametric representation!

Plane and Intersection



Orthographic View Volume

- View-volume plane equations
 - left plane
 - right plane
 - bottom plane
 - top plane
 - front plane
 - back plane
- Assume all the normals point into the view volume
- x left = 0
- - x + right = 0
- y bottom = 0
- $\bullet y + top = 0$
- z near = 0

• z + far = 0

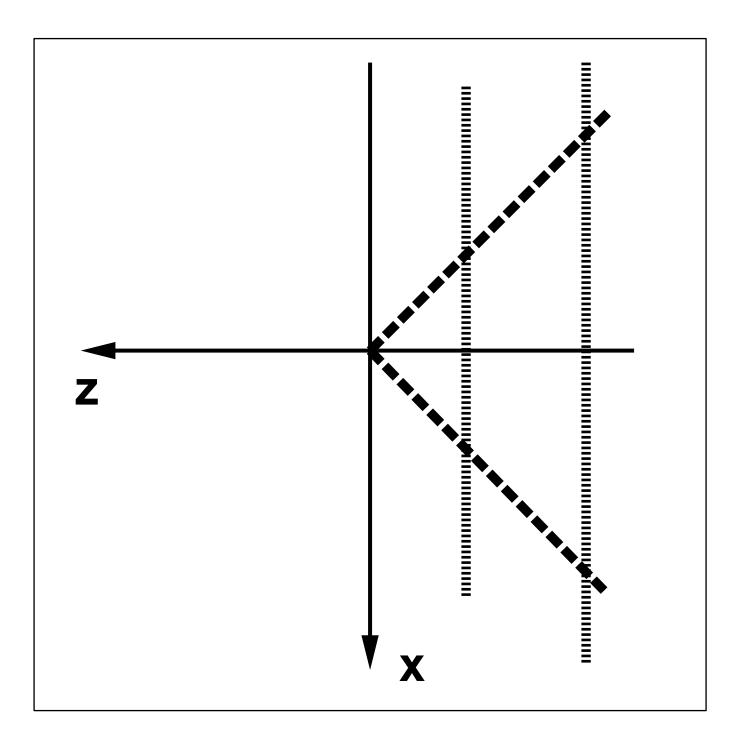
Perspective View Volume

- Again, six planes !
- x + (left * z)/(near) = 0
- - x (right * z)/(near) = 0
- y + (bottom * z)/(near) = 0
- -y (top * z)/(near) = 0
- z near = 0
- z + far = 0

3D Clipping

- Make use of plane equations
- Determine the sign of the plane equation
- If *plane*(p) > 0,
 then p is INSIDE!
- Clipping operations
 - point
 - line
 - polygon
 - complicated objects
- Clipping algorithms
- View volume clipping
- 2D algorithms can be generalized to 3D
 - Cohen-Sutherland line-clipping
 - Sutherland-Hodgeman algorithm

View Volume Projection



View Volume Projection

