

# DSSS, Viterbi Algorithm, MAC

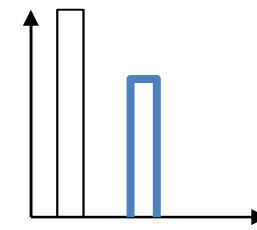
Jie Gao

9/17/09

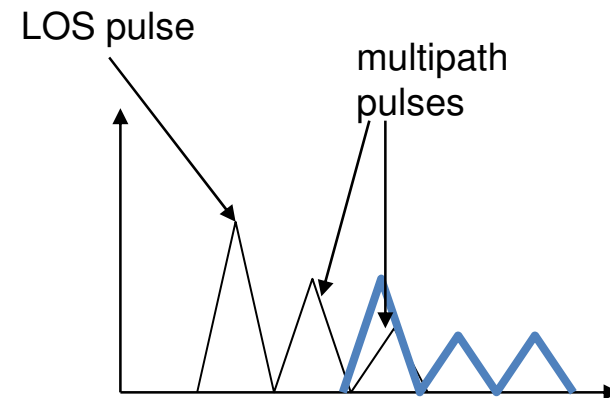
Acknowledgement: Slides borrowed from Richard Yang @ Yale.

# Multipath Can Cause ISI

dispersed signal can cause interference between “neighbor” symbols, Inter Symbol Interference (ISI)



signal at sender



signal at receiver

LOS: Line Of Sight

# Viterbi algorithm

- Convolutional coding
- Applying Viterbi decoding algorithm to solve ISI problem: equalization.

# ISI Problem Formulation

- The problem: given received  $y[m]$ ,  $m = 1, \dots, L+2$ , where  $L$  is frame size and assume 3 delay taps (it is easy to generalize to  $D$  taps):

$$y[1] = x[1]h_0 + w[1]$$

$$y[2] = x[2]h_0 + x[1]h_1 + w[2]$$

$$y[3] = x[3]h_0 + x[2]h_1 + x[1]h_2 + w[3]$$

$$y[4] = x[4]h_0 + x[3]h_1 + x[2]h_2 + w[4]$$

$$y[5] = x[5]h_0 + x[4]h_1 + x[3]h_2 + w[5]$$

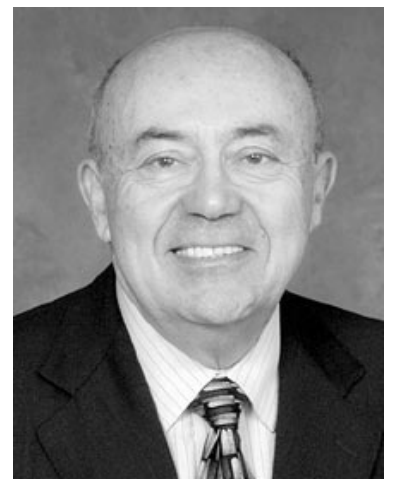
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$$y[L] = x[L]h_0 + x[L-1]h_1 + x[L-2]h_2 + w[L]$$

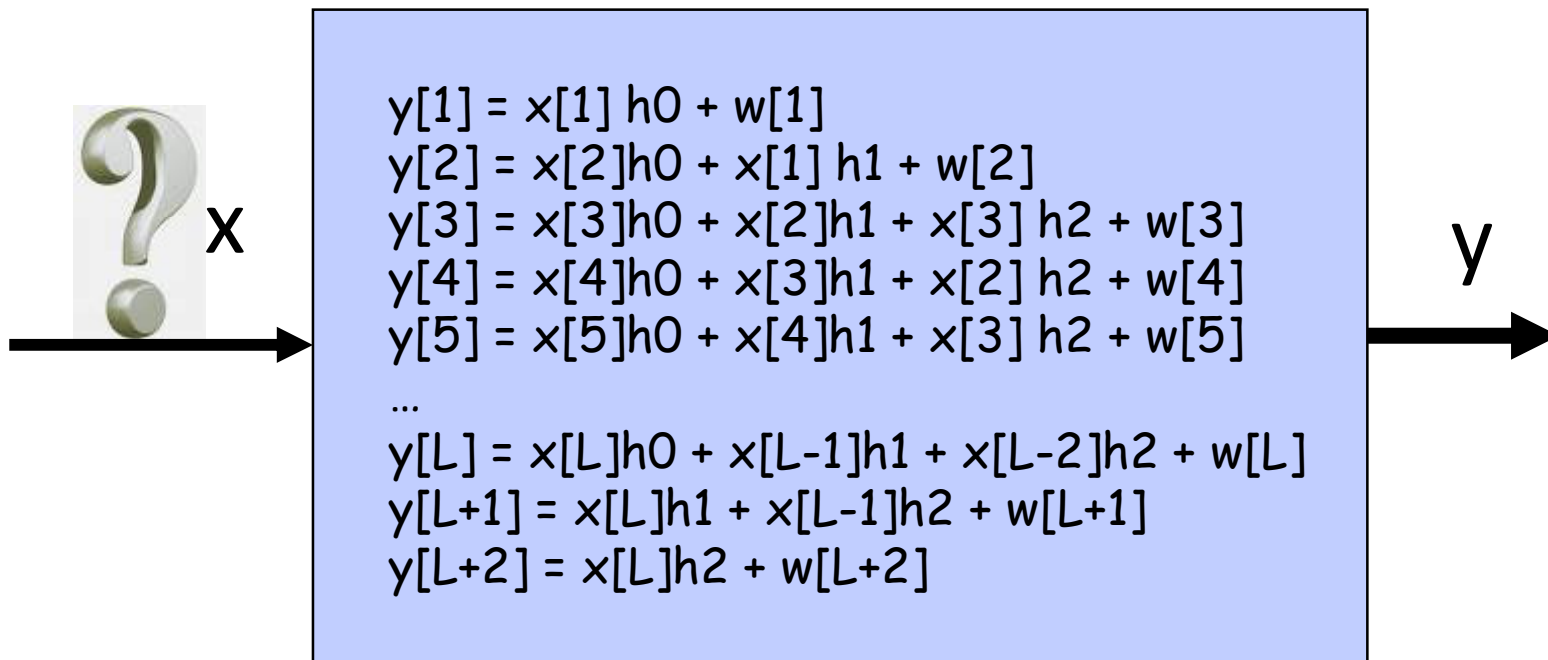
$$y[L+1] = x[L]h_1 + x[L-1]h_2 + w[L+1]$$

$$y[L+2] = x[L]h_2 + w[L+2]$$

determine  $x[1], x[2], \dots, x[L]$



# ISI Equalization: Given $y$ , what is $x$ ?



# Solution Technique

- Maximum likelihood detection:
  - if the transmitted sequence is  $x[1], \dots, x[L]$ , then there is a likelihood we observe  $y[1], y[2], \dots, y[L+2]$
  - we choose the  $x$  sequence such that the likelihood of observing  $y$  is the largest

$$y[1] = x[1] h_0 + w[1]$$

$$y[2] = x[2] h_0 + x[1] h_1 + w[2]$$

$$y[3] = x[3] h_0 + x[2] h_1 + x[1] h_2 + w[3]$$

$$y[4] = x[4] h_0 + x[3] h_1 + x[2] h_2 + w[4]$$

$$y[5] = x[5] h_0 + x[4] h_1 + x[3] h_2 + w[5]$$

...

$$y[L] = x[L] h_0 + x[L-1] h_1 + x[L-2] h_2 + w[L]$$

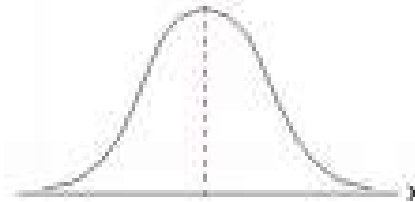
$$y[L+1] = x[L] h_1 + x[L-1] h_2 + w[L+1]$$

$$y[L+2] = x[L] h_2 + w[L+2]$$

# Likelihood

- For given sequence  $x[1], x[2], \dots, x[L]$
- Assume white noise, i.e, prob.  $w = z$  is

$$f(z) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{z^2}{2\sigma^2}}$$



- What is the likelihood (prob.) of observing  $y[1]$ ?

– it is the prob. of noise being  $w[1] = y[1] - x[1]$

$h_0$

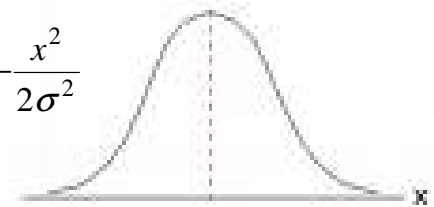
$$\frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{w[1]^2}{2\sigma^2}}$$

# Likelihood

- The likelihood of observing  $y[2]$ 
  - it is the prob. of noise being  $w[2] = y[2] - x[2]h_0 - x[1]h_1$ , which is

$$\frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{w[2]^2}{2\sigma^2}}$$

$$f(x) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{x^2}{2\sigma^2}}$$



- The overall likelihood of observing the whole  $y$  sequence ( $y[1], \dots, y[L+2]$ ) is the product of the preceding probabilities

# One Technique: Enumeration

foreach sequence  $(x[1], \dots, x[L])$

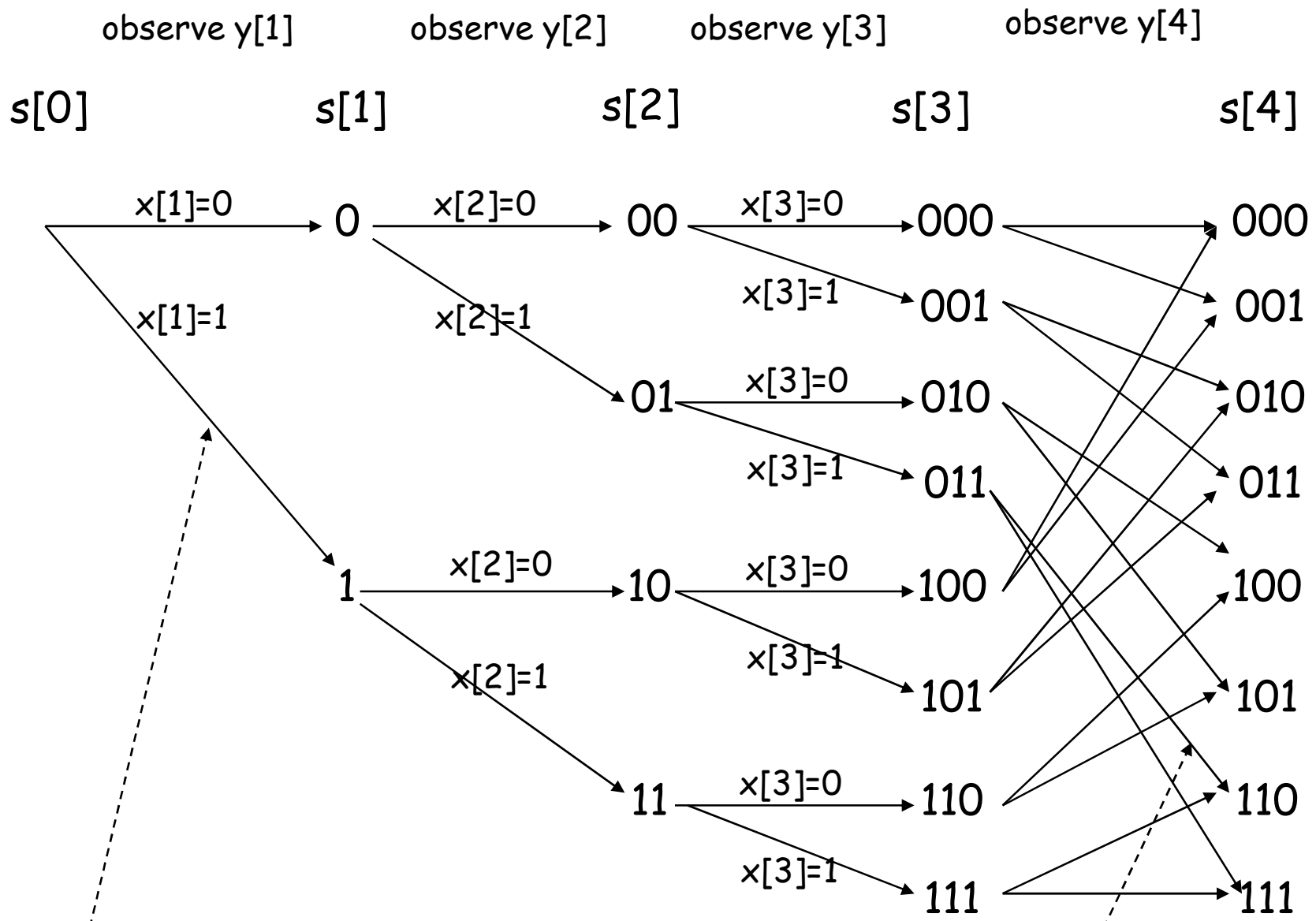
    compute the likelihood of observing the  $y$  sequence

pick the  $x$  sequence with the highest likelihood

Computational complexity: exponential in  $L$ .

# Viterbi Algorithm

- Objective: avoid the enumeration of the  $x$  sequences
- Key observation: the memory (state) of the wireless channel is only 3 (or generally  $D$  for  $D$  taps)
- Let  $s[0], s[1], \dots$  be the states of the channel as symbols are transmitted
  - $s[0]$ : initial state---empty
  - $s[1]$ :  $x[1]$  is transmitted, two possibilities: 0, or 1
  - $s[2]$ :  $x[2]$  is transmitted, four possibilities: 00, 01, 10, 11
  - $s[3]$ :  $x[3]$  is transmitted, eight possibilities: 000, 001, ..., 111
  - $s[4]$ :  $x[4]$  is transmitted, eight possibilities: 000, 001, ..., 111
- We can construct a state transition diagram
- If we know the  $x$  sequence we can construct  $s$ , and vice versa



prob. of observing  $y[1]$ :  
 $w[1] = y[1] - x[1]h_0$

prob. of observing  $y[2]$ :  
 $w[2] = y[2] - x[1]h_0 - x[2]h_1$

prob. of observing  $y[4]$ :  
 $w[4] = y[4] - x[4]h_0 - x[3]h_1 - x[2]h_2$

# Viterbi Algorithm

- Each path on the state-transition diagram corresponds to a  $x$  sequence
  - each edge has a probability
  - the product of the probabilities on the edges of a path corresponds to the likelihood that we observe  $y$  if  $x$  is the sequence sent
- Then the problem becomes identifying the path with the largest product of probabilities

# Viterbi Algorithm: Largest Product to Shortest Path

- If we take  $-\log$  of the probability of each edge, the problem becomes identifying the shortest path problem!
- Solve with dynamic programming.

# Viterbi Algorithm: Summary

- Invented in 1967
- Utilized in CDMA, GSM, 802.11, Dial-up modem, and deep space communications
- Also commonly used in
  - speech recognition,
  - computational linguistics, and
  - bioinformatics

Original paper: Andrew J. Viterbi. Error bounds for convolutional codes and an asymptotically optimum decoding algorithm, April 1967

<http://ieeexplore.ieee.org/search/wrapper.jsp?arnumber=1054010>