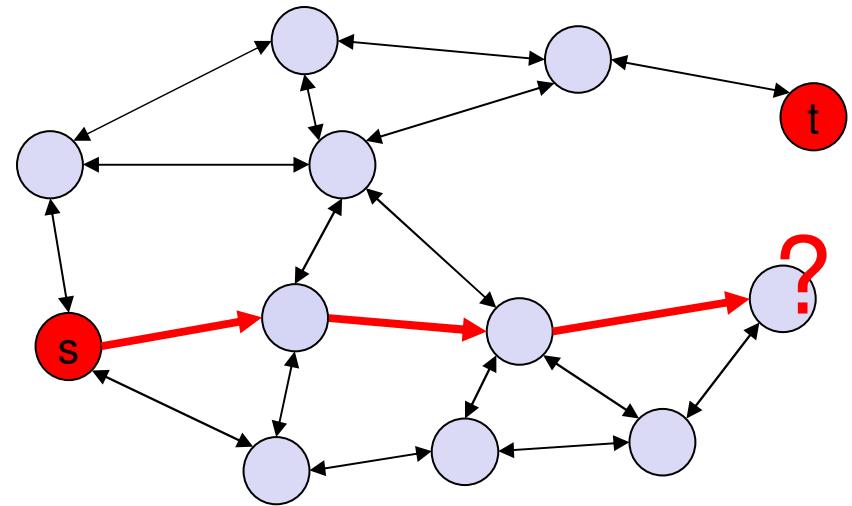
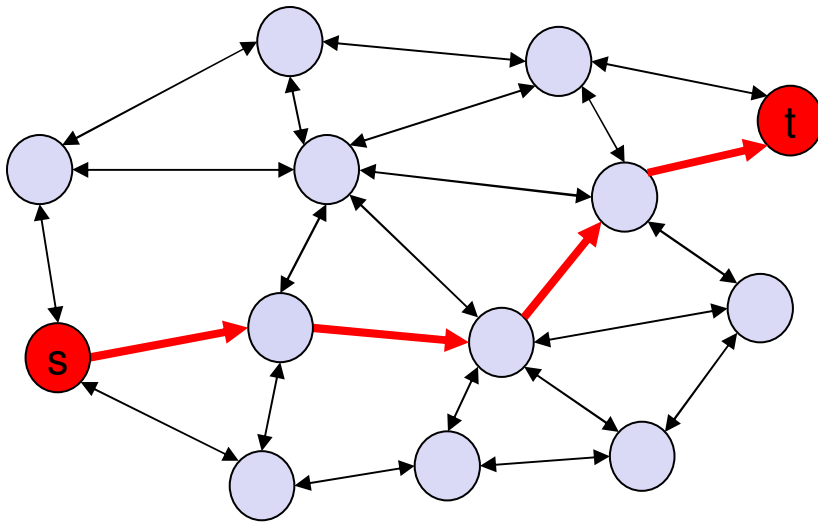

A brief overview of geographical routing

Geographical routing may get stuck

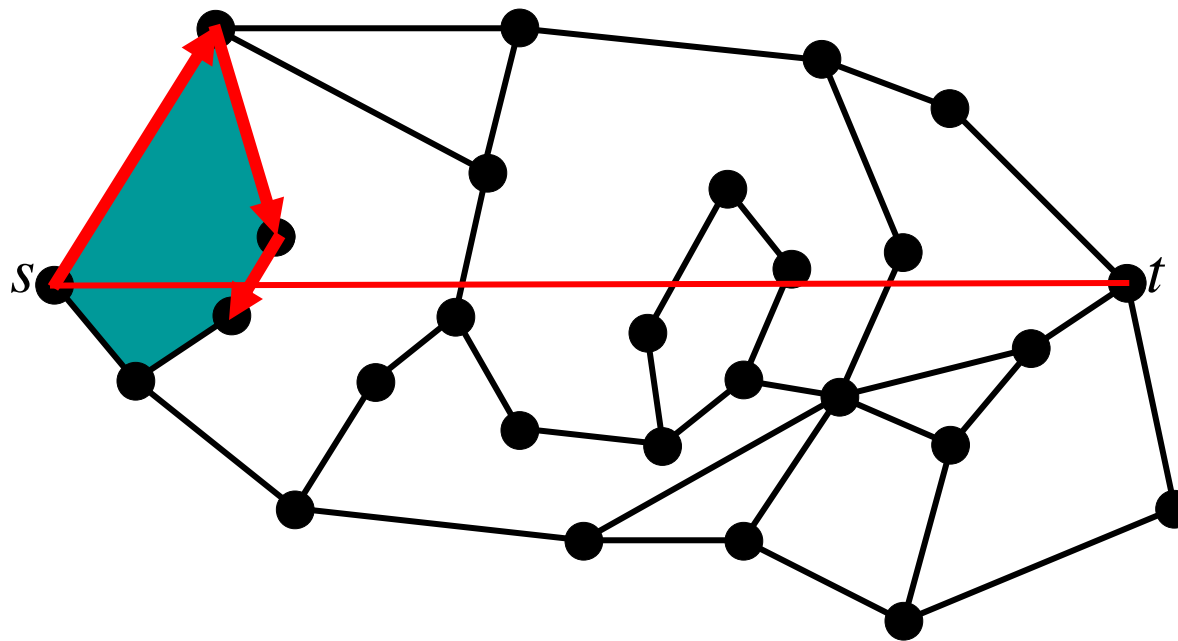
- Geographical routing may get stuck at a node whose neighbors are all further away from the destination than itself.



Send packets to the neighbor **closest** to the destination

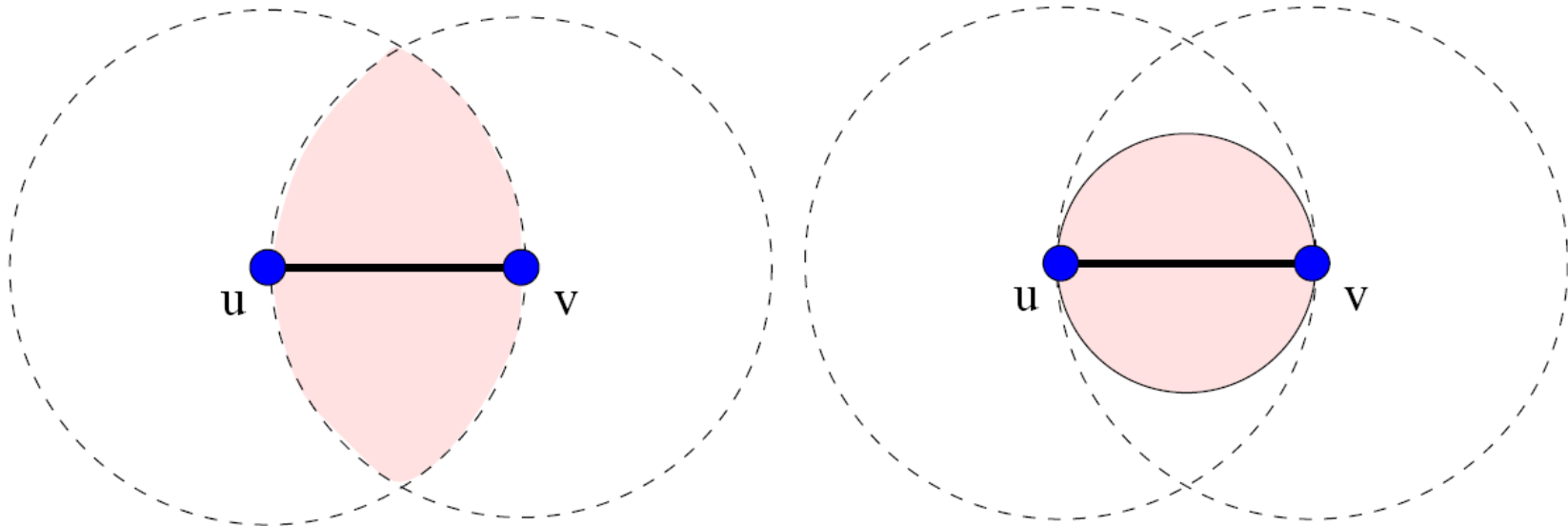
Face Routing

- Keep left hand on the wall, walk until hit the straight line connecting source to destination.
- Then switch to the next face.

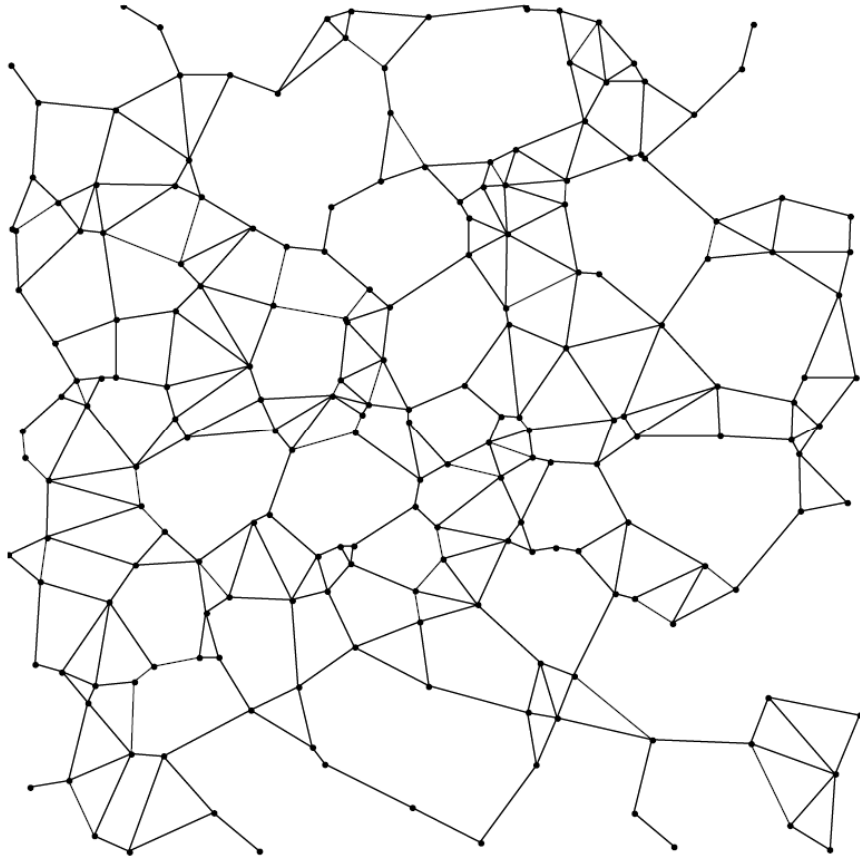


Relative Neighborhood Graph and Gabriel Graph

- Relative Neighborhood Graph (RNG) contains an edge uv if the lune is empty of other points.
- Gabriel Graph (GG) contains an edge uv if the disk with uv as diameter is empty of other points.
- Both can be constructed in a distributed way.

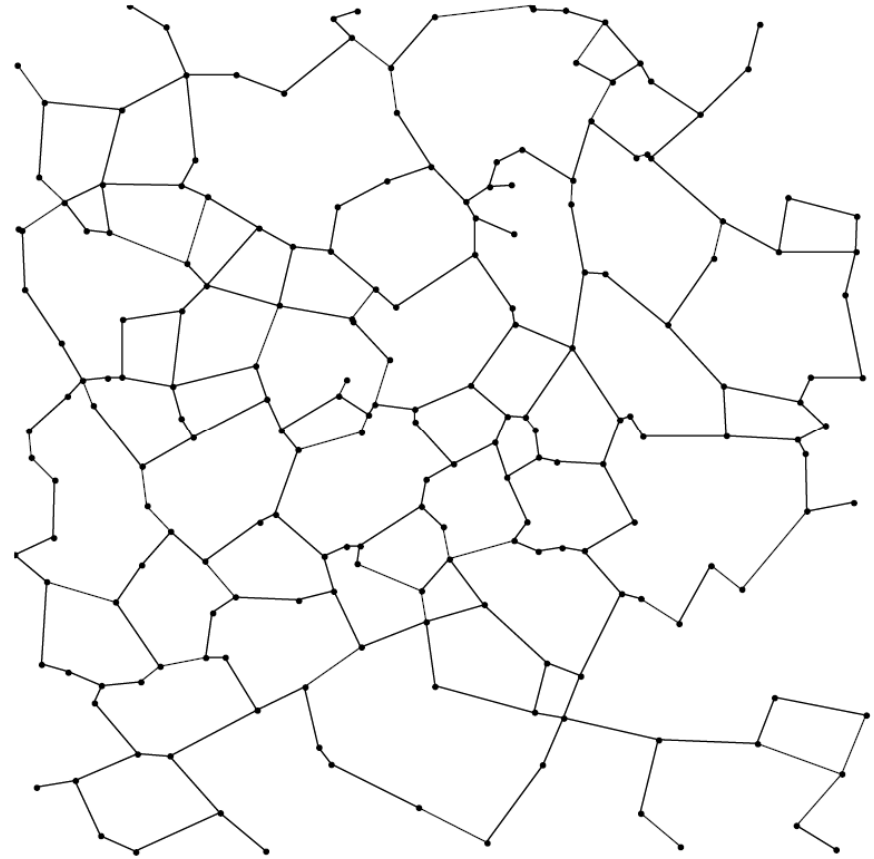


An example of GG and RNG



GG

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RNG

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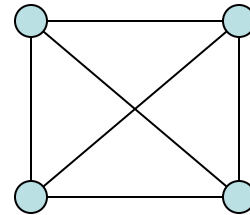
Two problems remain in geographical routing

- Both RNG and GG remove some edges → a short path may not exist!
- The shortest path on RNG or GG might be much longer than the shortest path on the original network.
- Even if the planar subgraph contains a short path, can greedy routing and face routing find a short one?

Tackle problem I: Find a planar spanner

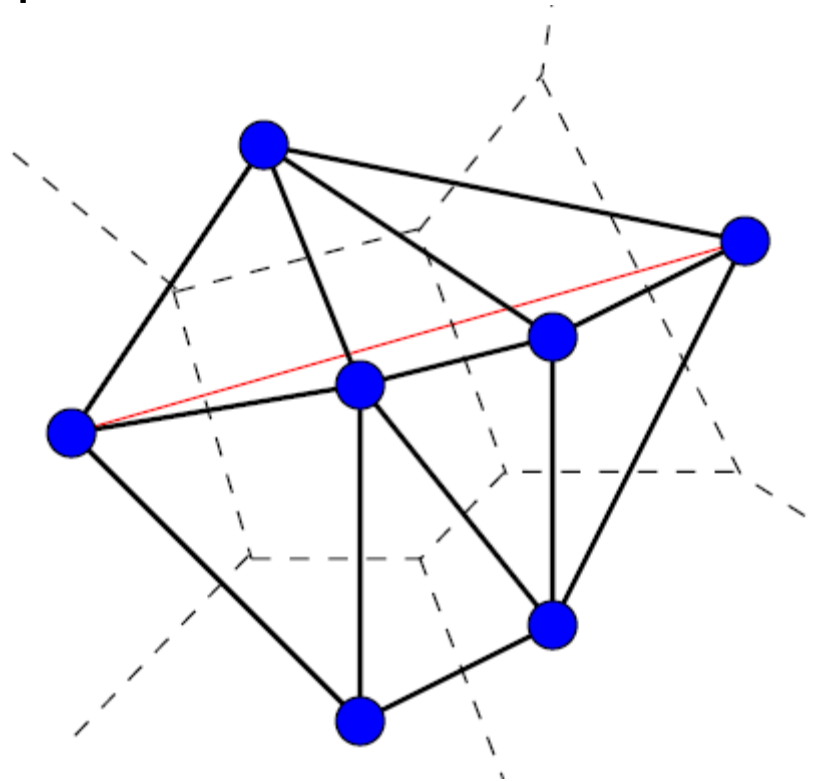
Find a good subgraph

- Goal: a **planar spanner** such that the shortest path is at most α times the shortest path in the unit disk graph.
 - **Euclidean spanner**: The shortest path length is measured in total Euclidean length.
 - **Hop spanner**: The shortest path length is measured in hop count.
- α : spanning ratio.
 - Euclidean spanning ratio $\geq \sqrt{2}$
 - Hop spanning ratio ≥ 2 .
- Let's first focus on Euclidean spanner.



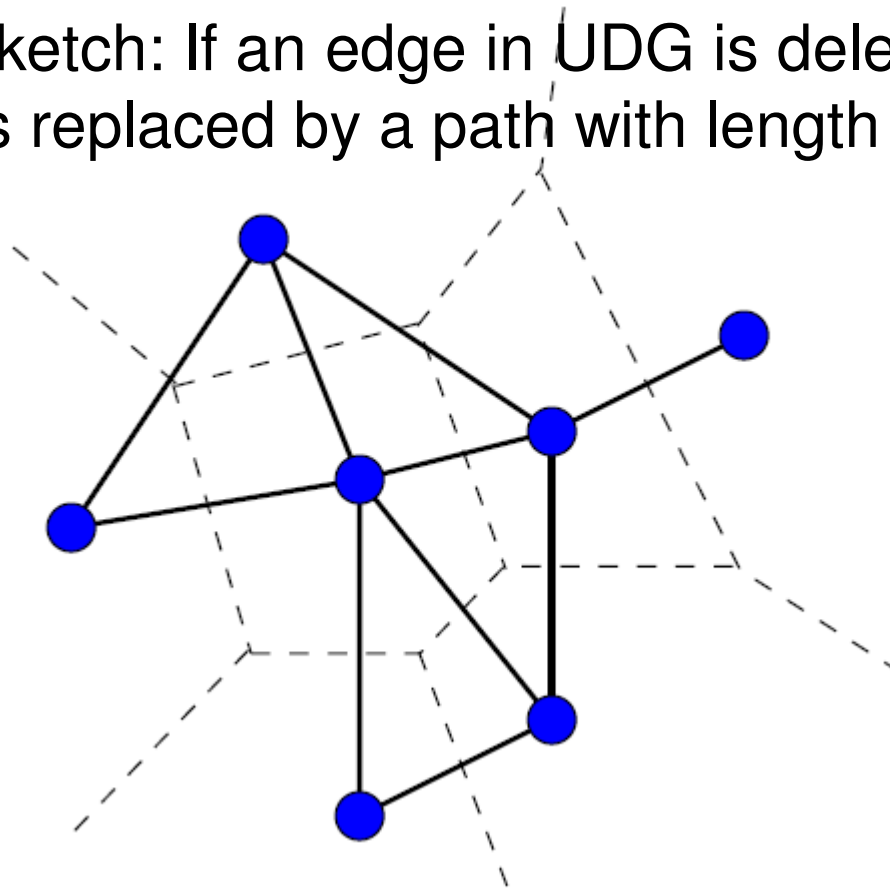
Delaunay triangulation is an Euclidean spanner

- DT is a 2.42-spanner of the Euclidean distance.
- For any two nodes uv , the Euclidean length of the shortest path in DT is at most 2.42 times $|uv|$.



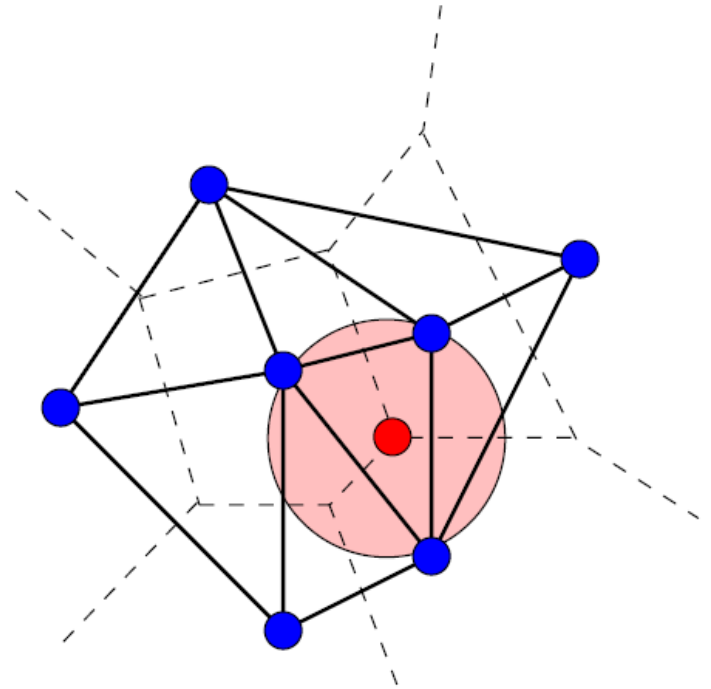
Restricted Delaunay graph

- Keep all the Delaunay edges no longer than 1.
- Claim: RDG is a 2.42-spanner (in total Euclidean length) of the UDG.
- Proof sketch: If an edge in UDG is deleted in RDG, then it's replaced by a path with length at most 2.42 longer.



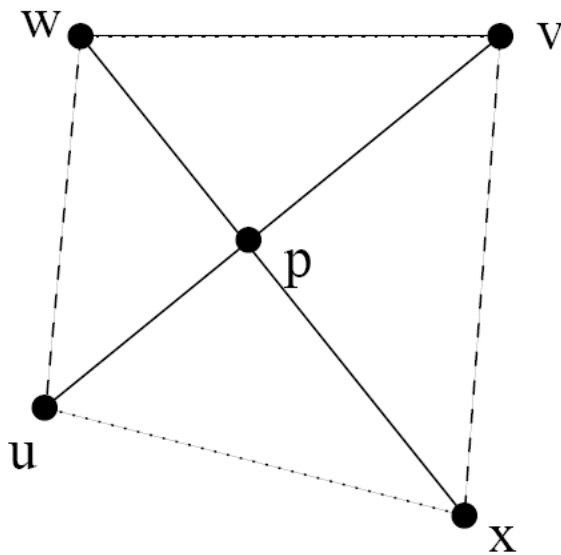
Construction of RDG

- Easy to compute a superset of RDG: Each node computes a local Delaunay of its 1-hop neighbors.
 - A global Delaunay edge is always a local Delaunay edge, due to the empty-circle property.
 - A local Delaunay may not be a global Delaunay edges.
- What if the superset has crossing edges?



Crossing Lemma

- **Crossing lemma:** if two edges cross in a UDG, then one node has edges to the three other nodes in UDG.



$$|wv| \leq |wv| + |vp| + |vp|$$

$$|vx| \leq |vp| + |xp|$$

$$\rightarrow |wv| + |vx| \leq |wv| + |vx| \leq 2$$

$$\text{Also, } |wv| + |ux| \leq |wv| + |ux| \leq 2$$

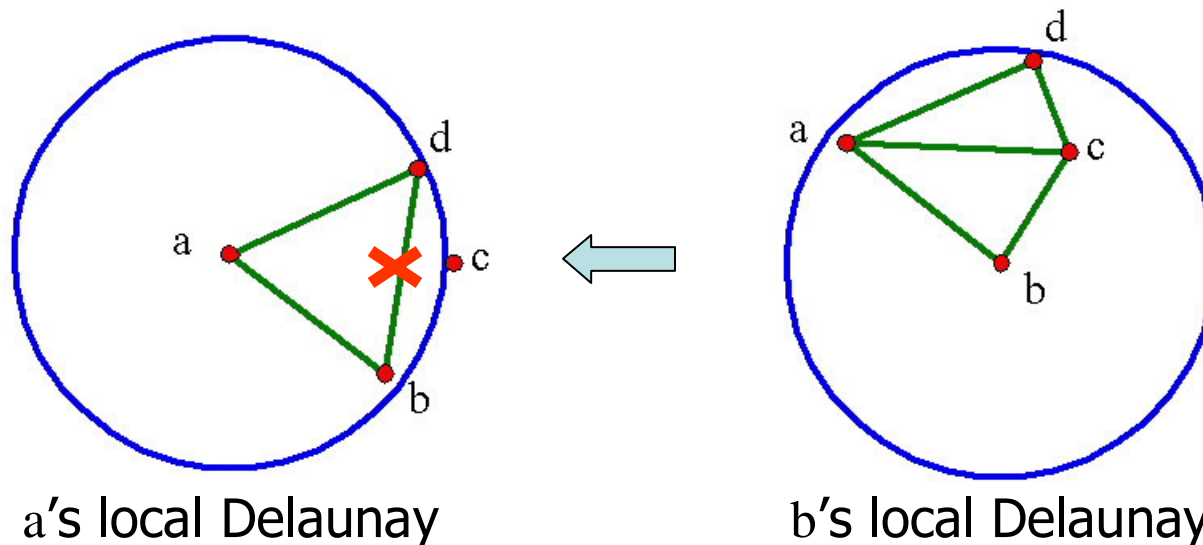
There must be 2 edges on the quad adjacent to the same node.

Detect crossings between local delaunay edges

- By the crossing Lemma: if two edges cross in a UDG, one of them has 3 nodes in its neighborhood and can tell which one is **not** Delaunay.
- Neighbors exchange their local DTs to resolve inconsistency.
 - A node tells its 1-hop neighbors the non-Delaunay edges in its local graph.
 - A node receiving a “forbidden” edge will delete it from its local graph.
- Completely distributed and local.

RDG construction

- 1-hop information exchange is sufficient.
 - Planar graph;
 - All the short Delaunay edges are included.
 - We may have some planar non-Delaunay edges but that does not hurt spanning property.

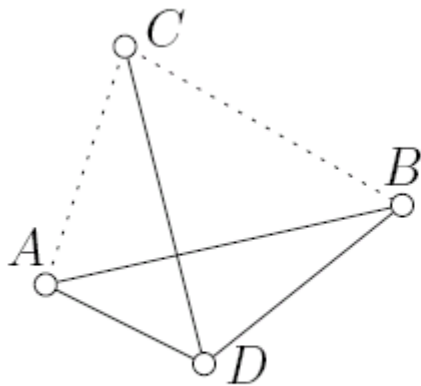


More on RDG construction

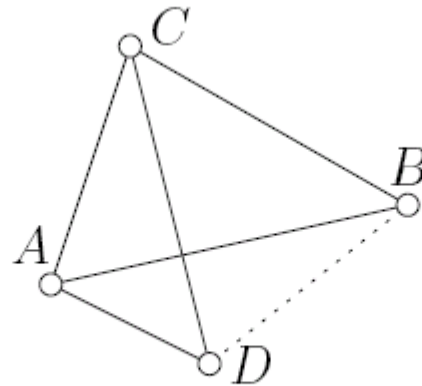
- RDG can be constructed without the full location information.
- Only local angle information suffices.
- Key operation: If two edges in the unit-disk graph cross, **remove** the one that is **not** in the Delaunay triangulation.
- How to tell that an edge is **not** in the Delaunay triangulation?

Removing non-Delaunay edges

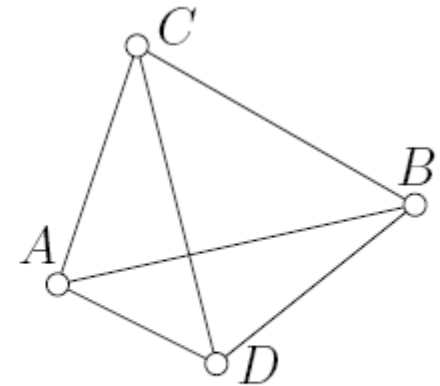
If two edges AB , CD cross, there are only three cases:



(i)



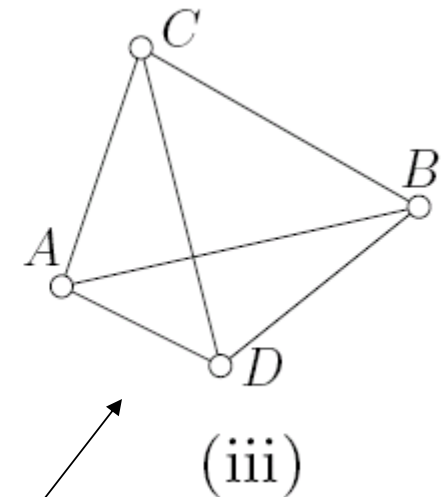
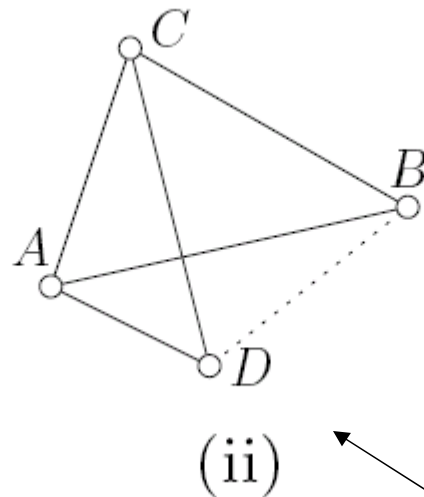
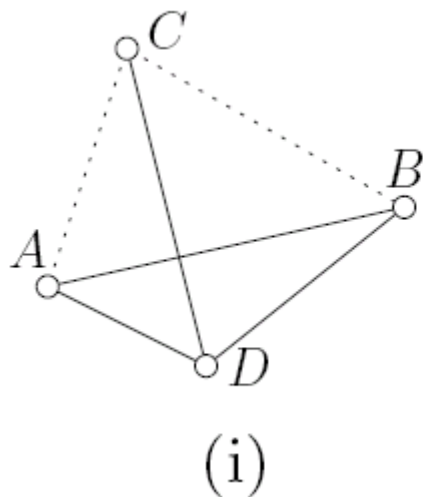
(ii)



(iii)

Removing non-Delaunay edges

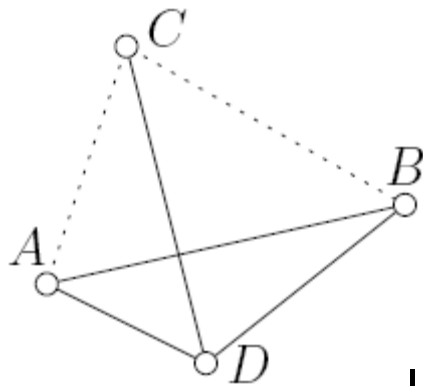
If two edges AB , CD cross, there are only three cases:



With angle info, the shape is fixed!
Node C can tell which edge is not Delaunay.

Removing non-Delaunay edges

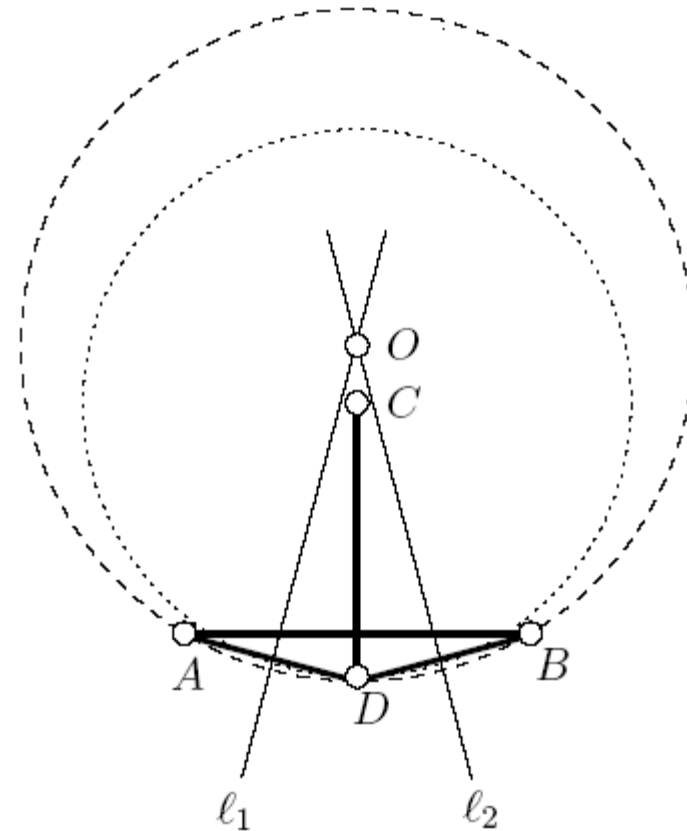
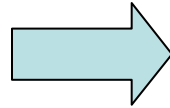
Case (i) : Use the “empty-circle” test of Delaunay triangulation



(i)

$$|AC| > 1 \geq |CD|$$

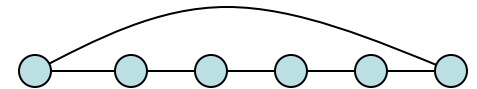
$$|BC| > 1 \geq |CD|$$



Conclusion: The edge AB is not a Delaunay edge.

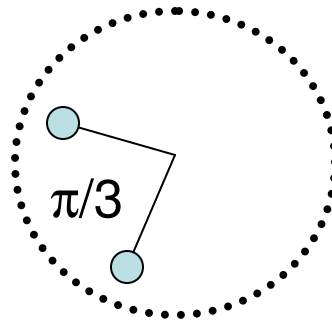
Find a hop spanner

- Restricted Delaunay graph is not a hop spanner.
 - Take n nodes uniformly in a segment of length 1. The hop count can be as large as $n-1$.
- Reduce the density of the sensors.
 - Use clustering to reduce density.
 - Compute RDG on the subset to get a hop spanner.
 - Clustering also reduce interference and enables efficient resource reuse such as bandwidth.



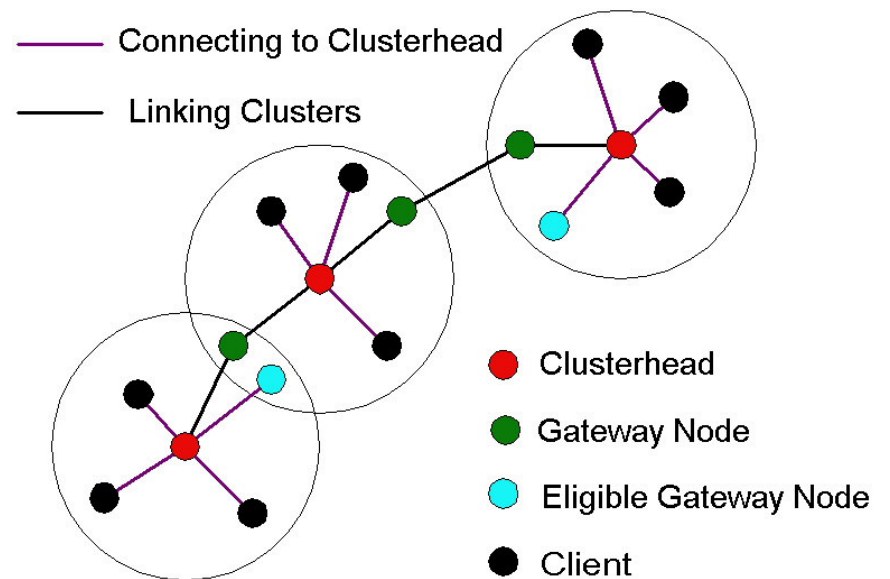
Reduce node density

- Find a subset of nodes, called **clusterheads**
 - Each node is directly connected to at least 1 clusterhead.
 - No two clusterheads are connected.
- Use a greedy algorithm. Pick a node as a clusterhead, remove all the 1-hop neighbors, continue.
- Constant density: ≤ 6 clusterheads in any unit disk.
 - The angle spanned by two clusterheads is at least $\pi/3$.



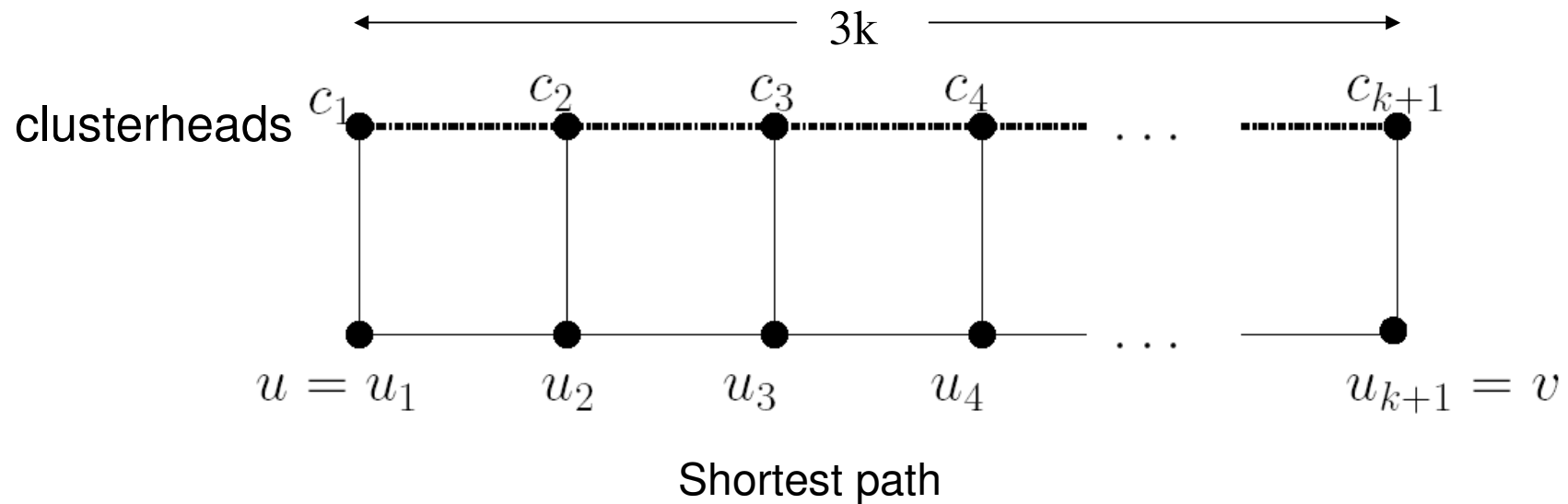
Connect clusterheads by gateways

- For two clusterheads, if their clients have an edge, then we pick one pair as **gateway** nodes.
- Notice that clusterheads x , y are within 3 hops to have a pair of gateways.
- There are constant clusterheads and gateways inside any unit disk.



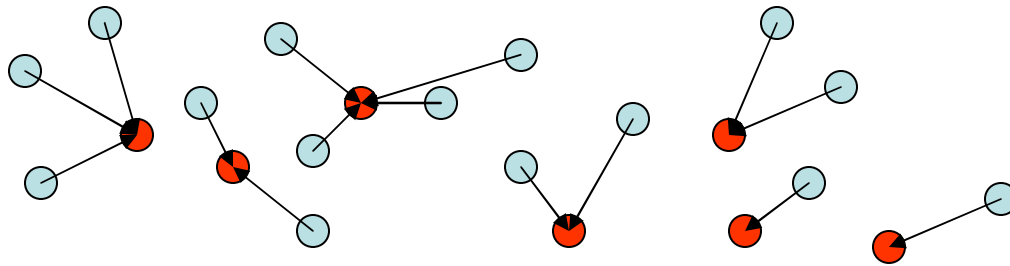
Path on clusterheads and gateways

- For two nodes u, v that are k hops away, there is a path through clusterheads and gateways with at most $3k+2$ hops.

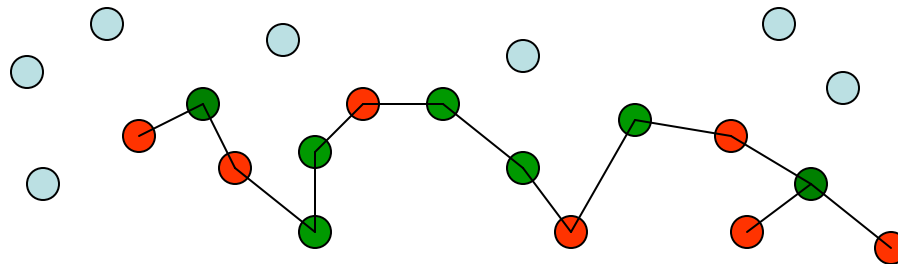


- Construct RDG on clusterheads and gateways, which have constant bounded density.

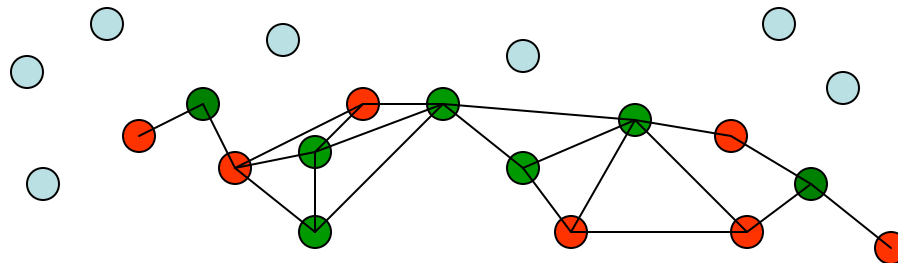
A Routing Graph Sample



Select clusterheads



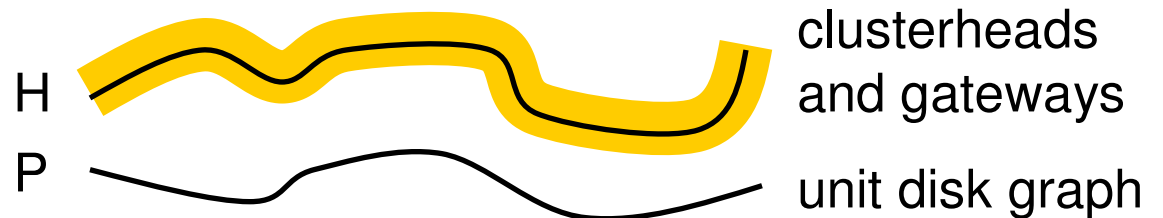
Clusterheads select gateways



RDG on clusterheads & gateways

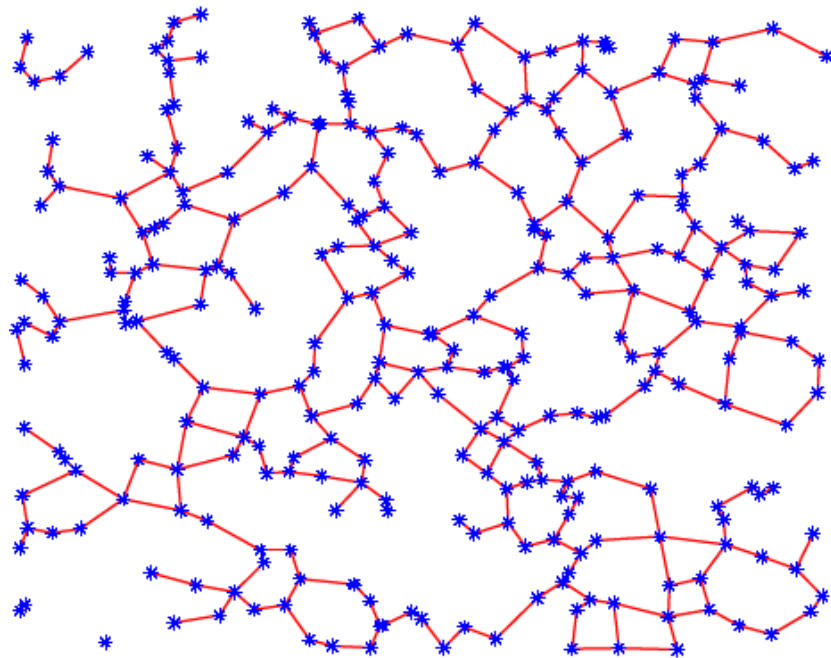
Restricted Delaunay graph

- Claim: (RDG on clusterheads and gateways + edges from clients to clusterheads) is a constant hop spanner of the original UDG.



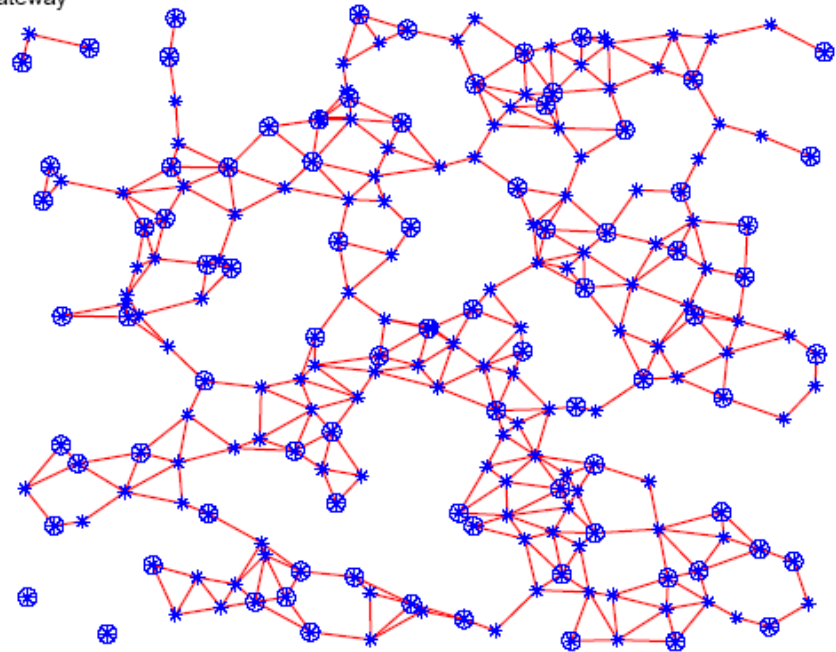
- Proof sketch:
 - The shortest path P in the unit disk graph has k hops.
 - Through clusterheads and gateways \exists a path Q with $\leq 3k+2$ hops.
 - Q's total Euclidean length is $\leq 3k+2$.
 - The shortest path on the RDG, H, has Euclidean length $\leq 2.42 \times (3k+2)$.
 - By constant density property a region with width 1 and length $2.42 \times (3k+2)$ has $O(k)$ nodes inside. So # hops of H is $O(k)$.
 - This concludes the hop spanner property.

Restricted Delaunay graph



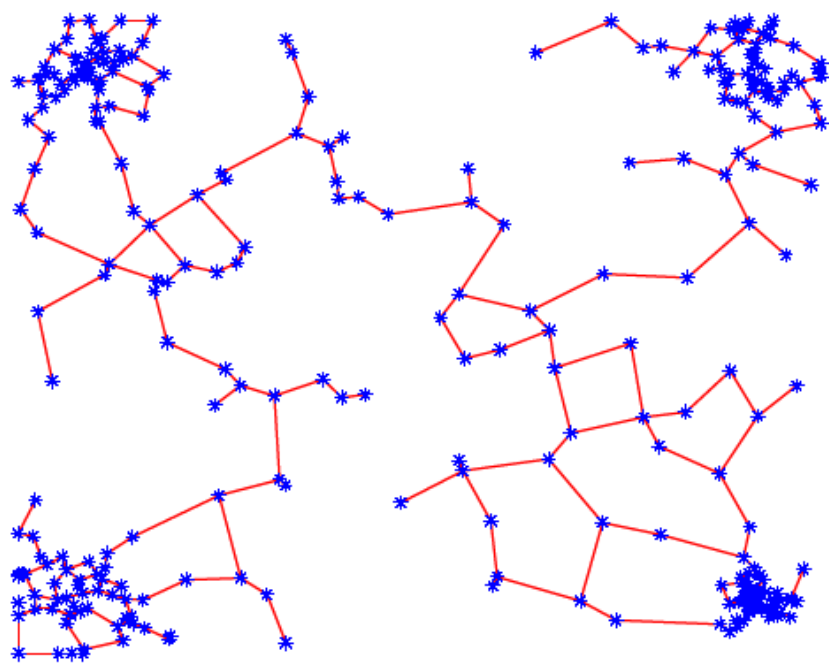
RNG

- ⊗ Clusterhead
- * Gateway



RDG

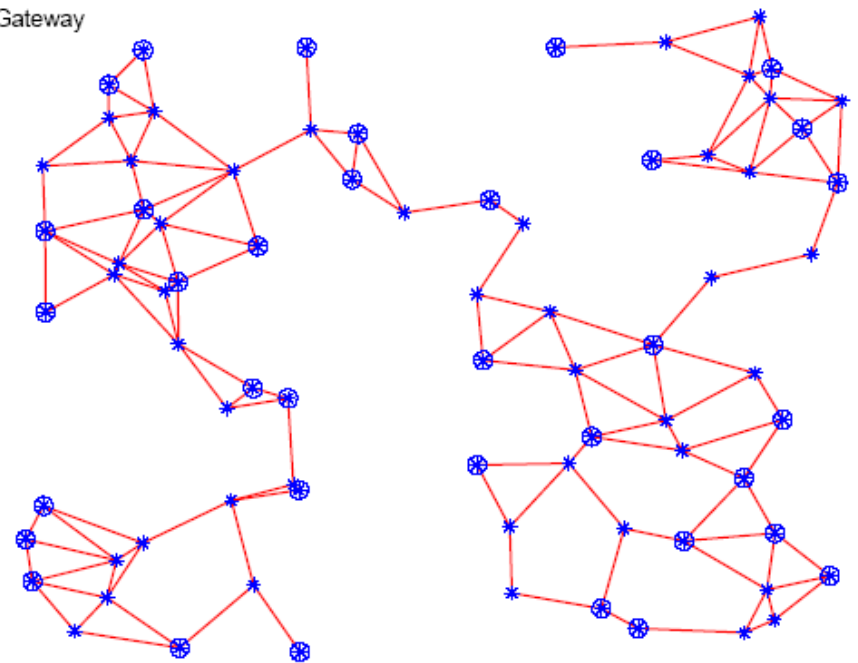
Restricted Delaunay graph



RNG

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- ⊗ Clusterhead
- * Gateway



RDG

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**Tackle problem II:
Improve face routing to find a short
path &
Geographic routing in practice**

Papers

Geographic routing in practice:

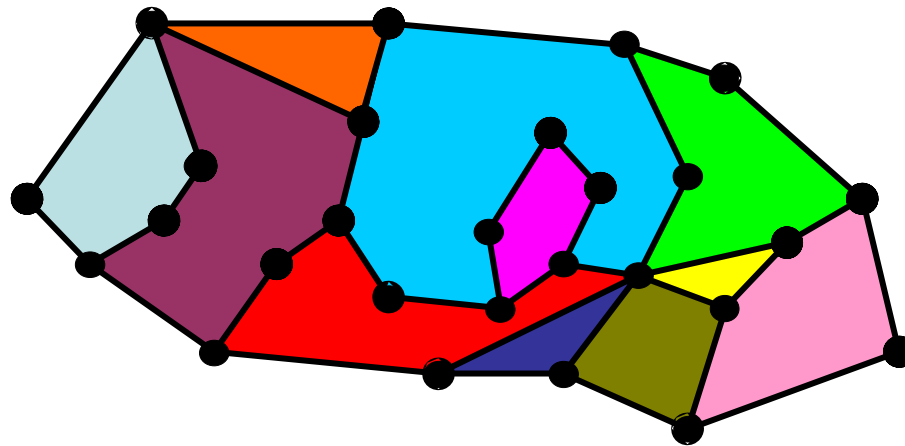
- Kim, Y.-J., Govindan, R., Karp, B., and Shenker, S., [On the Pitfalls of Geographic Face Routing](#), DIAL-M-POMC'05.

Virtual coordinates:

- Ananth Rao, Christos Papadimitriou, Scott Shenker, and Ion Stoica, [Geographical routing without location information](#), Proc. MobiCom'03, pages 96 - 108, 2003.

Overview of geographical routing

- Routing with geographical location information.
 - Greedy forwarding.
 - If stuck, do face routing on a planar sub-graph.

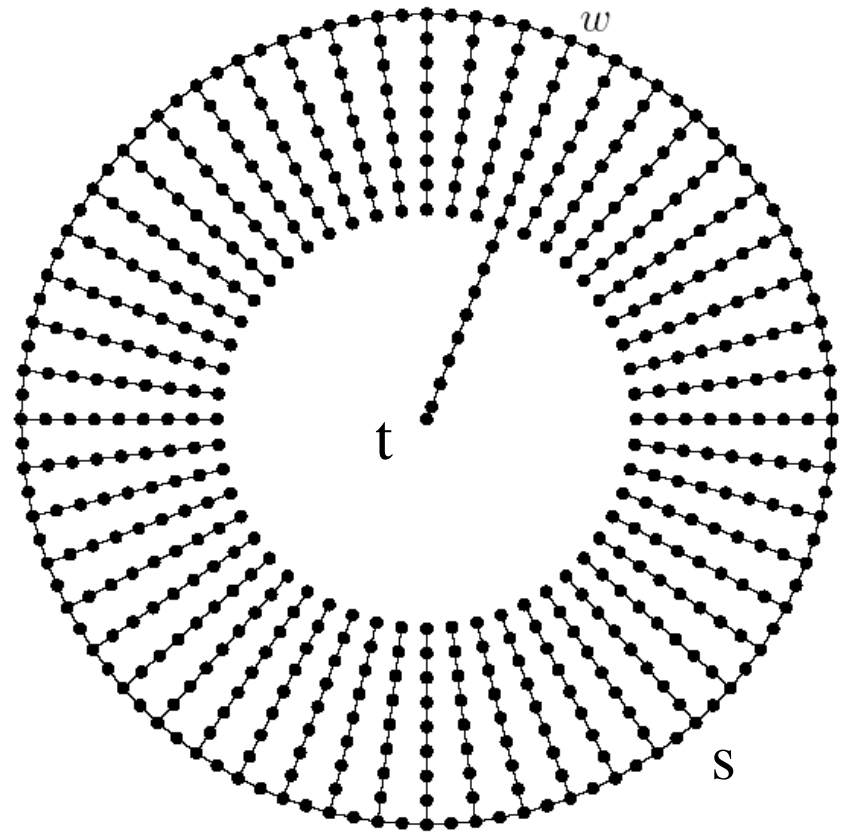


Overview of last lecture

- How to find a planar subgraph?
 - Use distributed construction: relative neighborhood graph, Gabriel graph, etc.
 - A planar subgraph that **contains** a short path: restricted Delaunay graph: short Delaunay edges.
- Big problem: how is the performance of geo-routing?
 - Can we always **find** a short path?

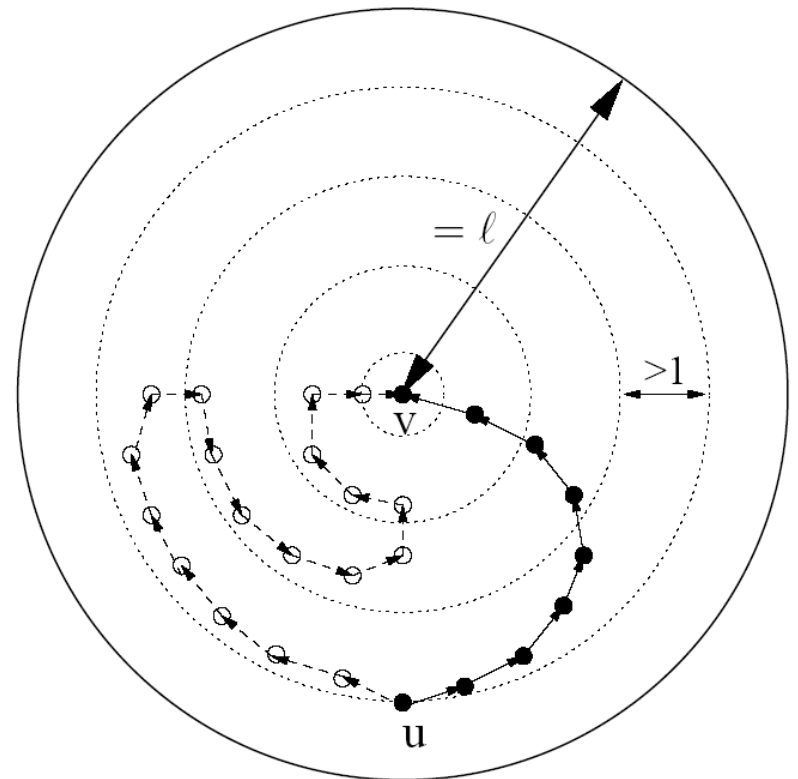
Bad news: Lower bound of localized routing

- Any deterministic or randomized **localized** routing algorithm takes a path of length $\Omega(k^2)$, if the optimal path has length k .
- The adversary decides where the chain w is. Since we store no information on nodes, in the worst case we have to visit about $\Omega(k)$ chains and pay a cost of $\Omega(k^2)$.



Good news: greedy forwarding is optimal

- If greedy routing gets to the destination, then the path length is at most $O(k^2)$, if the optimal path has length k .
- $|uv|$ is at most k . On the greedy path, every other node is not visible, so they are of distance at least 1 away. By a packing lemma, there are at most $O(k^2)$ nodes inside a disk of radius k .



How is face routing? How is greedy + face routing?